OPERATING INSTRUCTIONS

BATTERY LOADING:
(FOR MAXIMUM PERFORMANCE, USE ALKALINE BATTERIES. (NOT INCLUDED))
Remember to take out the batteries after playing.
- Do not mix old and new batteries.
- Do not mix alkaline, standard (Carbon-Zinc) or rechargeable (Nickel-Cadmium) batteries.

INSTALLING THE BATTERIES:
1. Unscrew to open the Battery Case Cover of the base of the robot.
2. Insert 6 'C' size alkaline batteries as indicated inside following the (+) (-) signs polarity. (See Diagram 1)
3. Replace the Battery Case Cover.

ATTACHING THE REAR WHEEL:
Push and slide the rear wheel into the back of the robot. (See Diagram 2)

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(Diagram 1)

(Diagram 2)

FLASHING LIGHT

Flashing light flashes when arms move.
TRACK MOVEMENT

- Move Forward
- Turn Right (Forward)
- Turn Right (Backward)
- Rotate Right
- Move Backward
- Move Left (Forward)
- Move Left (Backward)
- Rotate Left
**ARMS MOVEMENT**

- Press UP & DOWN buttons to move the arms
- Press OPEN & CLOSE buttons to move the arms

**Arms Up & Down**

**Arms Open & Close**

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**HINTS FOR BETTER PERFORMANCE**

<table>
<thead>
<tr>
<th>TROUBLE</th>
<th>REASON</th>
<th>INSTRUCTION</th>
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</thead>
<tbody>
<tr>
<td>When robot runs in opposite direction from your command.</td>
<td>Misplacement of batteries.</td>
<td>Place batteries as marked (+)(-) in battery compartment.</td>
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<tr>
<td>When robot does not operate properly or does not move.</td>
<td>Insufficient battery contact due to rust.</td>
<td>Remove rust with sand paper or a clean cloth.</td>
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<tr>
<td>When robot goes too slow.</td>
<td>Batteries too week.</td>
<td>Replace with new batteries.</td>
</tr>
<tr>
<td>When flashing light goes dim.</td>
<td>Batteries too week.</td>
<td>Replace with new batteries.</td>
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</table>
SPOT LIGHT

Spot light comes "ON" while Robot runs forward and backward or turns left and right

If the Spot Light is out of order, Unscrew to open the case cover and replace the light bulb. (8V base type: E10)

THE CONTROLLER

Step 1

Step 2

After playing, wrap the cable around the controller holder at the back of the robot to store the controller.